



How Low Can We Go? Mínímízíng Interaction Samples for Configurable Systems



All errors and outrageous lies are mine, and only mine

Co-conspirators:



Domíník Krupke, Ahmad Moradí, Míchael Perk, Phíllíp Keldeních, Gabríel Gehrke, Sebastían Kríeter, Thomas Thüm, Sándor P. Fekete



Testing configurable systems is critical

CM US World Politics Business Opinion Health Entertainment Style Travel Sports Underscored

Toyota recalls 280,000 vehicles because they may 'creep forward' in neutral

By Diksha Madhok, CNN 2 minute read · Updated 9:48 AM EST Thu February 22, 2024

f 🐰 🗹 👁



The company will inform the owners of recalled vehicles by late April and update the software for the transmission, Toyota said.

The recall is one of three in the United States that the company announced Wednesday.

Toyota said it was recalling another 19,000 vehicles over a software problem that means "the rearview image may not display within the period of time required by certain US safety regulations after the driver shifts the vehicle into reverse, increasing the risk of a crash while backing the vehicle."

That safety recall involves certain Mirai and Lexus LS, LC, ES models in North America, made between 2023 and 2024, it added.

Additionally, some 4,000 Toyota Camry and Camry Hybrid vehicles are also being recalled over safety issues with the head restraints on rear fold-down seats that "increase the risk of injury during certain collisions."

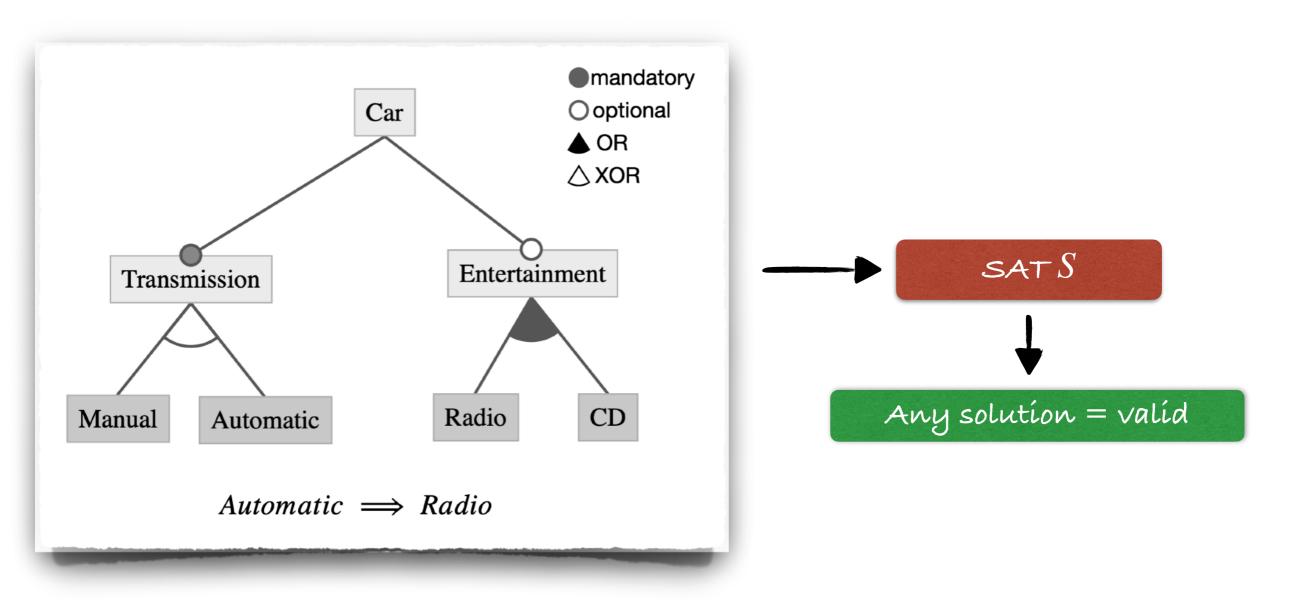
Toyota is the world's biggest automaker by sales, but it risks becoming bogged down in safety scandals.



Technische Universität Braunschweig

How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12

The Feature Model (on <mark>binary features</mark>)



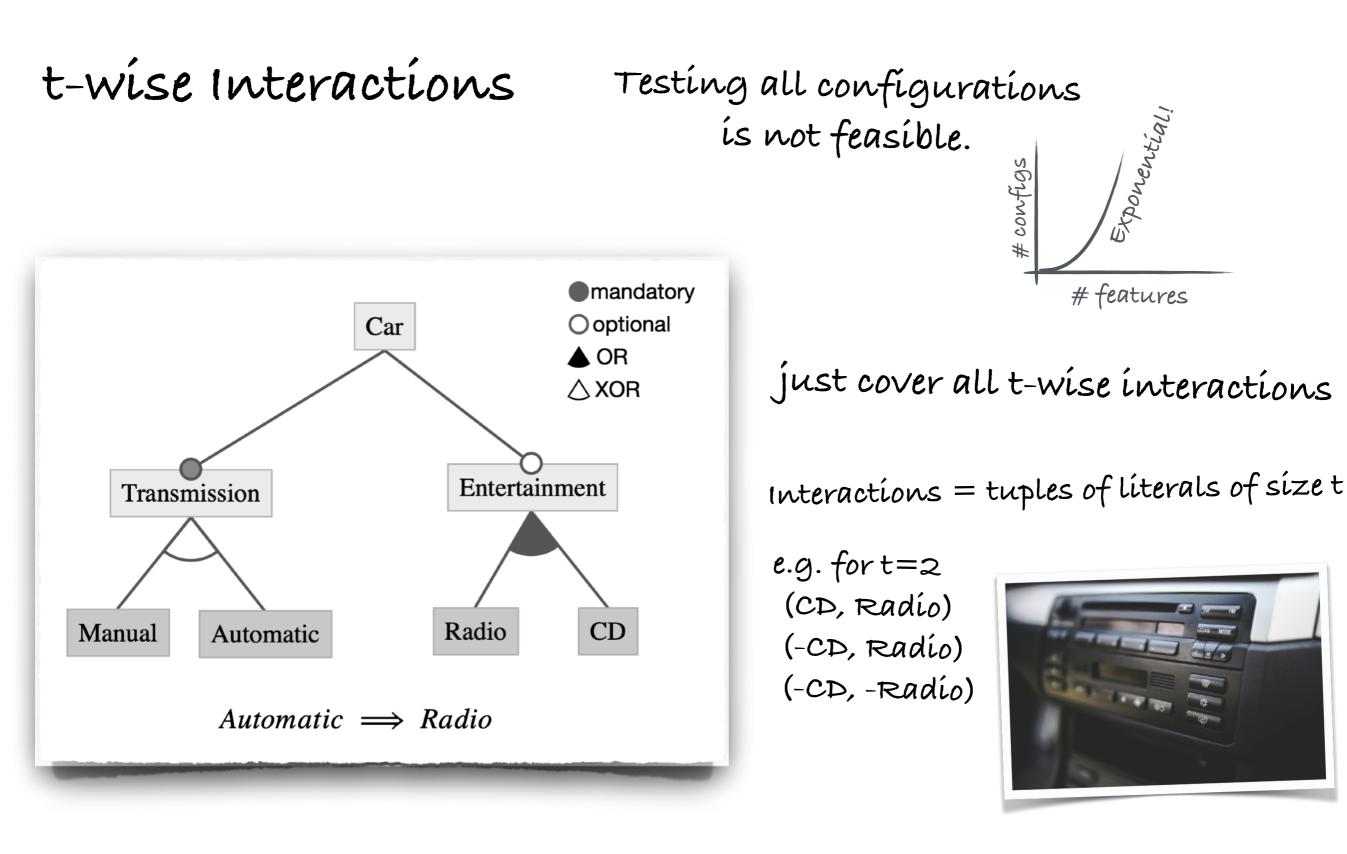


Technische

Universität

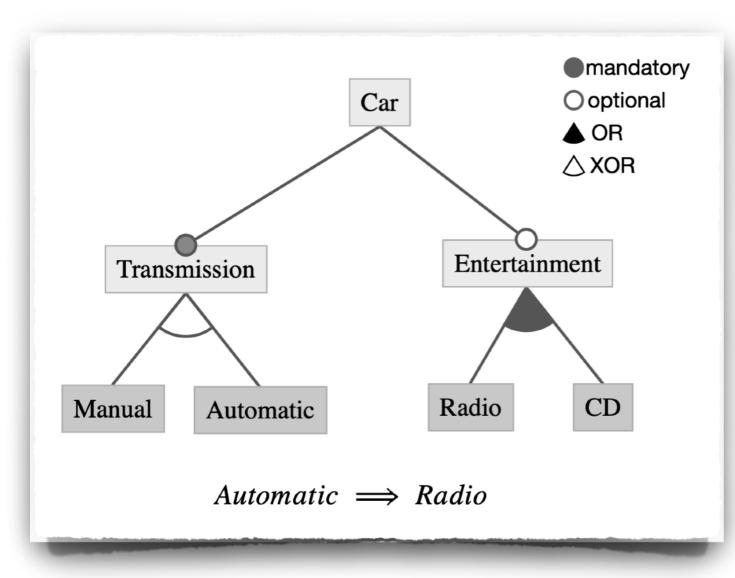
Braunschweig

How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12





(Complete) Paírwise-Interaction Sampling Problem t=2



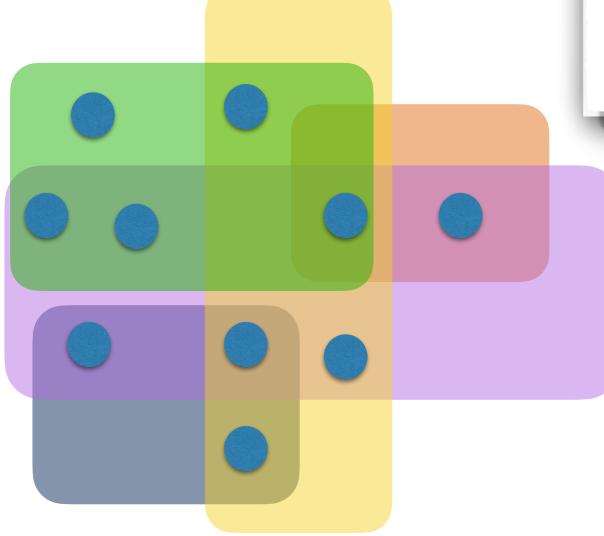
Features
$$F = \{1, ..., n\}$$

Líterals
 $L = \{-n, ..., -1, 1, ..., n\}$
Valíd Interactions $I \subsetneq L \times L$
Goal: Find minimum cardinality
set of configurations that covers I
 \checkmark We call this a sample



Technische Universität Braunschweig

The Set Cover Problem



Inapproximability results [edit]

When *n* refers to the size of the universe, Lund & Yannakakis (1994) showed that set covering cannot be approximated in polynomial time to within a factor of $\frac{1}{2} \log_2 n \approx 0.72 \ln n$, unless NP has quasi-polynomial time algorithms. Feige (1998) improved this lower bound to $(1 - o(1)) \cdot \ln n$ under the same assumptions, which essentially matches the approximation ratio achieved by the greedy algorithm. Raz & Safra (1997) established a lower bound of $c \cdot \ln n$, where *c* is a certain constant, under the weaker assumption that $P \neq NP$. A similar result with a higher value of *c* was recently proved by Alon, Moshkovitz & Safra (2006). Dinur & Steurer (2013) showed optimal inapproximability by proving that it cannot be approximated to $(1 - o(1)) \cdot \ln n$ unless P = NP.

https://en.wikipedia.org/wiki/Set_cover_problem

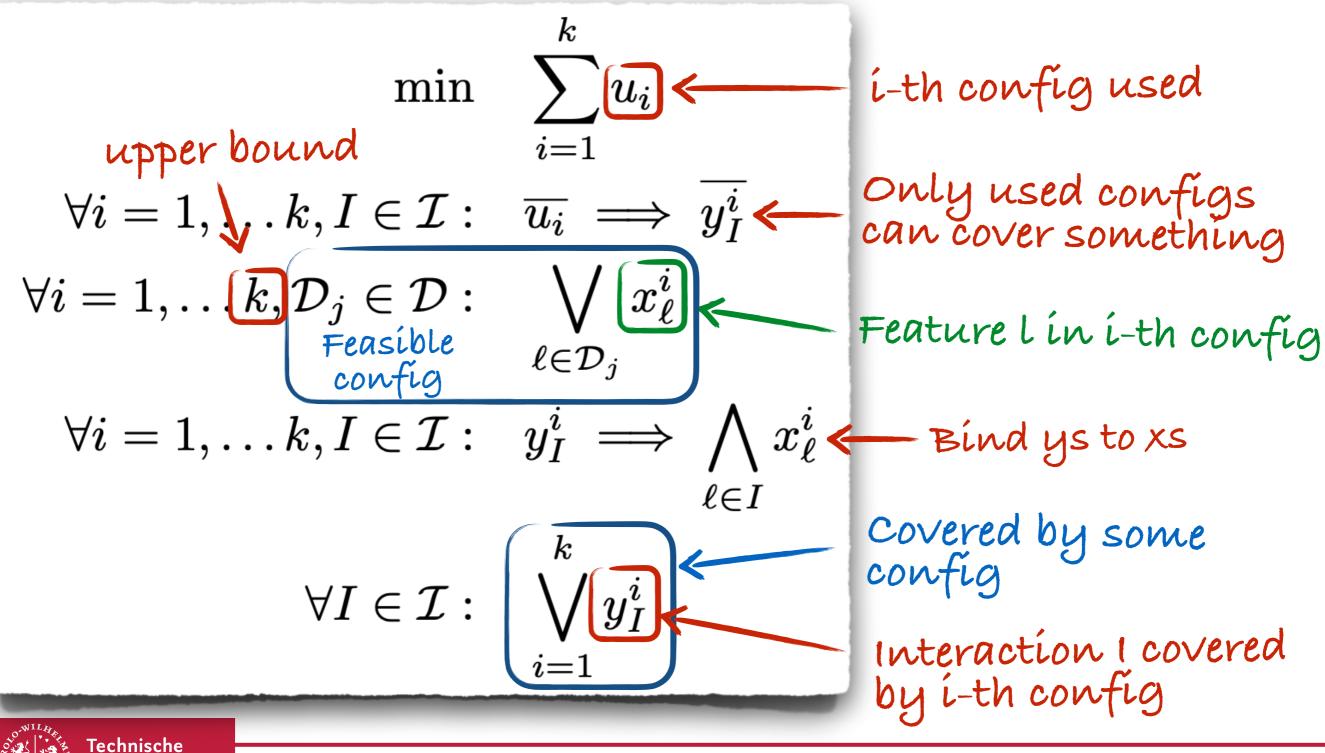
+Challenge 1: Elements NP-hard to ídentífy

+ Challenge 2: Exponentíal number of potentíal coveríng sets

ON LAND ON CHART



We can express the problem as a SAT-formula (plus objective) to solve for optimality!





Universität

Braunschweig

$$\begin{array}{rl} \min & \sum_{i=1}^{k} u_{i} \\ \forall i = 1, \dots, k, I \in \mathcal{I} : & \overline{u_{i}} \implies \overline{y_{I}^{i}} \\ \forall i = 1, \dots, k, \mathcal{D}_{j} \in \mathcal{D} : & \bigvee_{\ell \in \mathcal{D}_{j}} x_{\ell}^{i} \\ \forall i = 1, \dots, k, I \in \mathcal{I} : & y_{I}^{i} \implies \bigwedge_{\ell \in I} x_{\ell}^{i} \\ \forall I \in \mathcal{I} : & \bigvee_{i=1}^{k} y_{I}^{i} \end{array}$$



Why are symmetries so bad?

$$\begin{aligned} x_1^1 &:= 1 \quad x_2^1 := 1 \quad x_3^1 := 0 \quad x_4^1 := 1 \quad \cdots \\ x_1^2 &:= 0 \quad x_2^2 := 0 \quad x_3^2 := 0 \quad x_4^2 := 1 \quad \cdots \\ x_1^3 &:= 1 \quad x_2^3 := 0 \quad x_3^3 := 1 \quad x_4^3 := 0 \quad \cdots \\ x_1^4 &:= 0 \quad x_2^4 := 1 \quad x_3^4 := 0 \quad x_4^4 := 1 \quad \cdots \\ &\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \\ x_1^n &:= 1 \quad x_2^n := 1 \quad x_3^n := 0 \quad x_4^n := 0 \quad \cdots \end{aligned}$$

k! equivalent representations that look different to the solver!

10! = 3628800, 15! = 1.3076744e + 12, 20! = 2.432902e + 18



Technische

Universität

Braunschweig

Mutually Exclusive Interactions

cannot appear in same sample $(x_1 := 1, x_2 := 1)$ Cover in first configuration $(x_1 := 0, x_2 := 1)$ Cover in second configuration $(x_1 := 1, x_2 := 0)$ Cover in third configuration $(x_1 := 0, x_2 := 0)$ Cover in fourth configuration

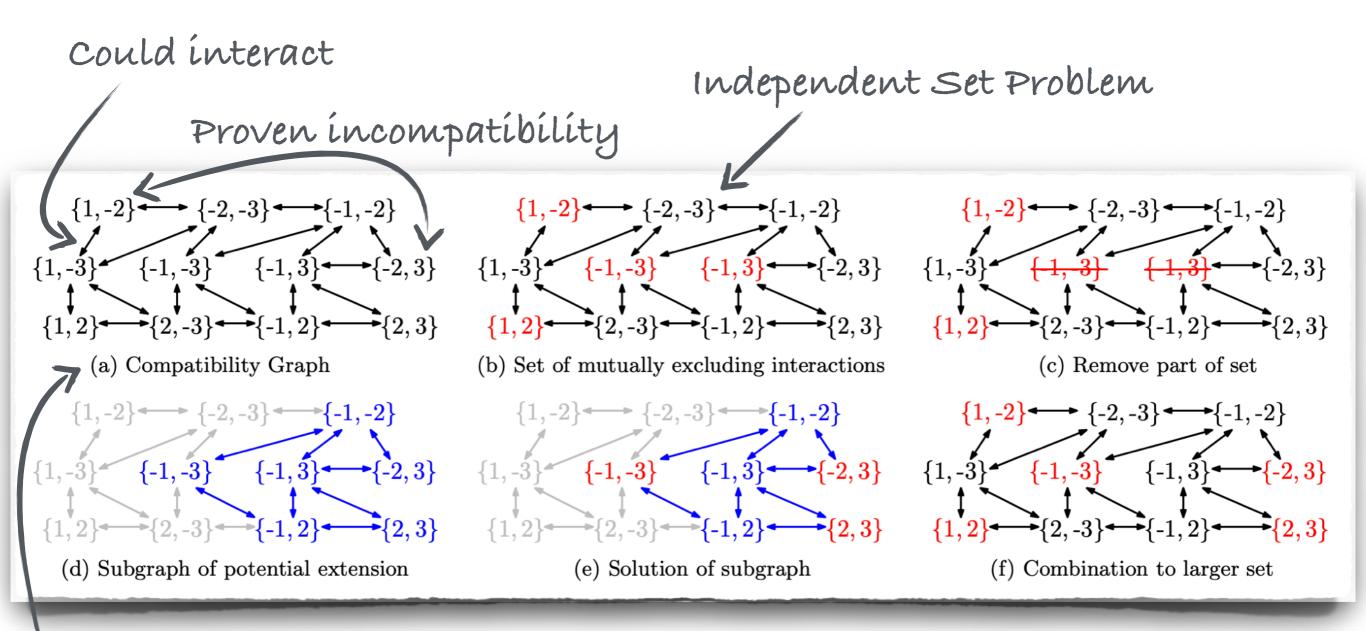
Can we do more? $(\neg x_1 \lor \neg x_2 \lor \neg x_3 \lor \neg x_4)$ $(x_1 := 1, x_2 := 1) \checkmark (x_3 := 1, x_4 := 1)$ $\xrightarrow{\text{mutually est set of interactions!}}$

ohoh... isn't that the max clique problem!?



How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12

Use a Large Neighborhood Search



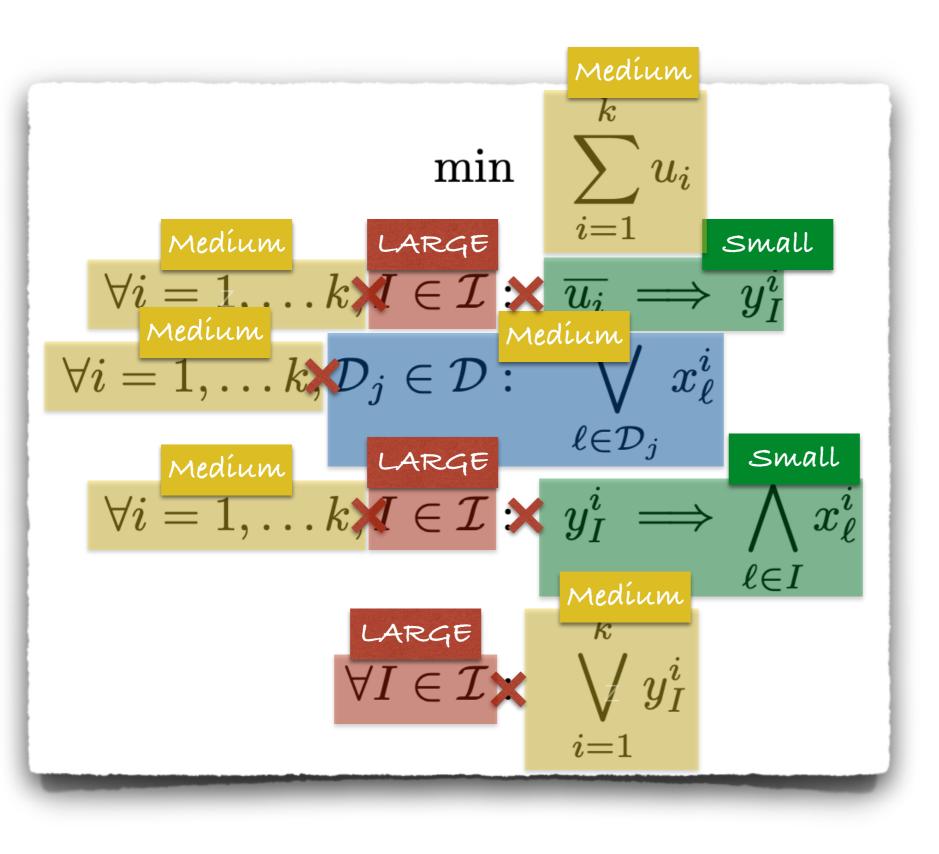
Inverse of incompatibility graph

Result is a lower bound!



Technische Universität Braunschweig

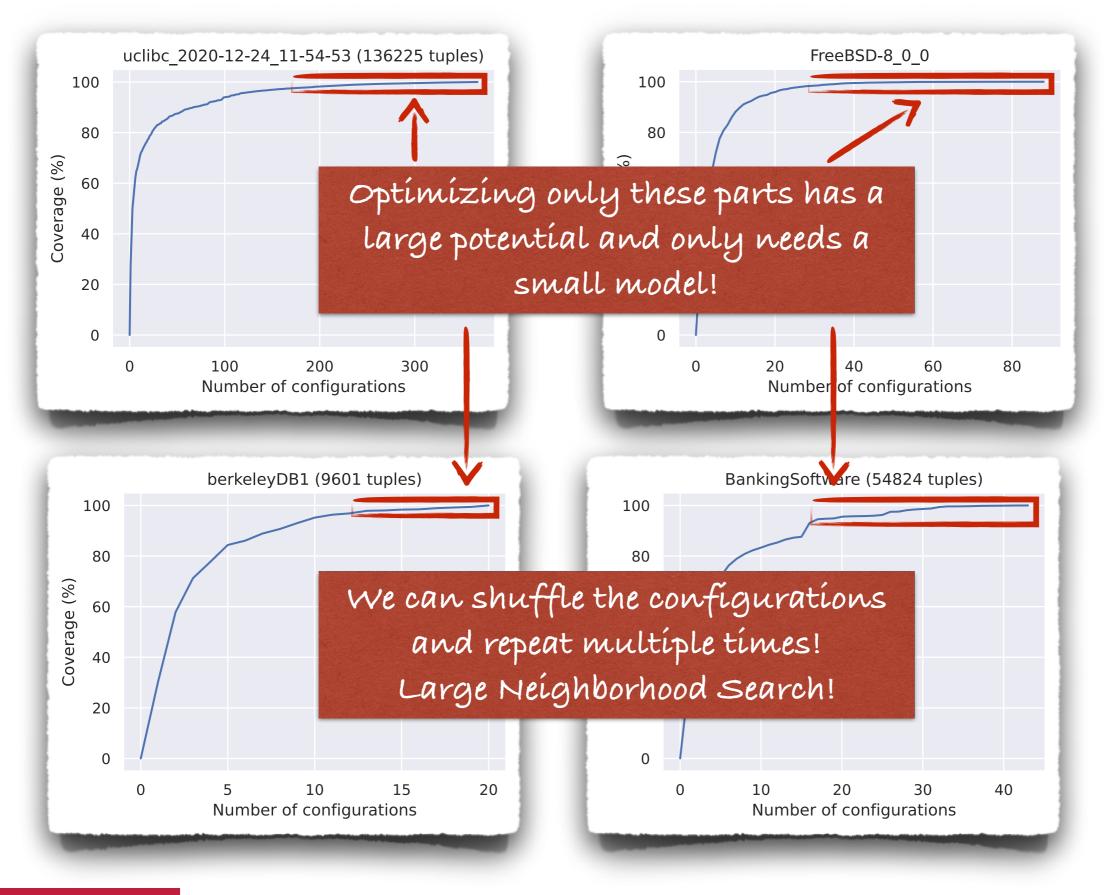
How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12



Next Problem. the size...



How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12





How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12 Clauses:

Features: $\mathcal{F} = \{1, 2, 3, 4\}$ $\mathcal{D} = \{\{1,2\},\{3,4\}\}$



Interactions:

 $\mathcal{F} = \{ \{3,4\}, \{1,-3\}, \{2,-4\}, \{1,3\}, \{-2,4\}, \{-1,4\}, \{2,4\}, \{1,2\}, \{1,-4\}, \{-2,-3\}, \{-1, \{-2,3\}, \{-1,3\}, \{3,-4\}, \{-3,4\}, \{2,-3\}, \{1,-2\}, \{1,4\}, \{2,3\}, \{-1,-4\}, \{-2,-4\}, \{-1,2\} \}$

Initial Sample:

(locally optimal) $S = \{\{1, 2, 3, 4\}, \{1, -2, 3, -4\}, \{1, -2, -3, 4\}, \{-1, 2, 3, 4\}, \{-1, 2, 3, -4\}, \{-1, 2, -3, 4\}\}\}$

DESTROY: Select random subset...

 $S' = \{\{1,2,-3,4\}, \{-1,2,3,4\}, \{-1,2,3,-4\}\}$

Removal leaves uncovered:

(much smaller!)

15

 $\mathcal{I}' = \{\{1,2\}, \{2,3\}, \{3,4\}, \{2,-4\}, \{-1,3\}, \{-1,-4\}\}$ REPAIR: Compute optimal sample for it ...

$$S'' = \{\{1,2,3,4\}, \{-1,2,-3,4\}\}$$

Build better sample:

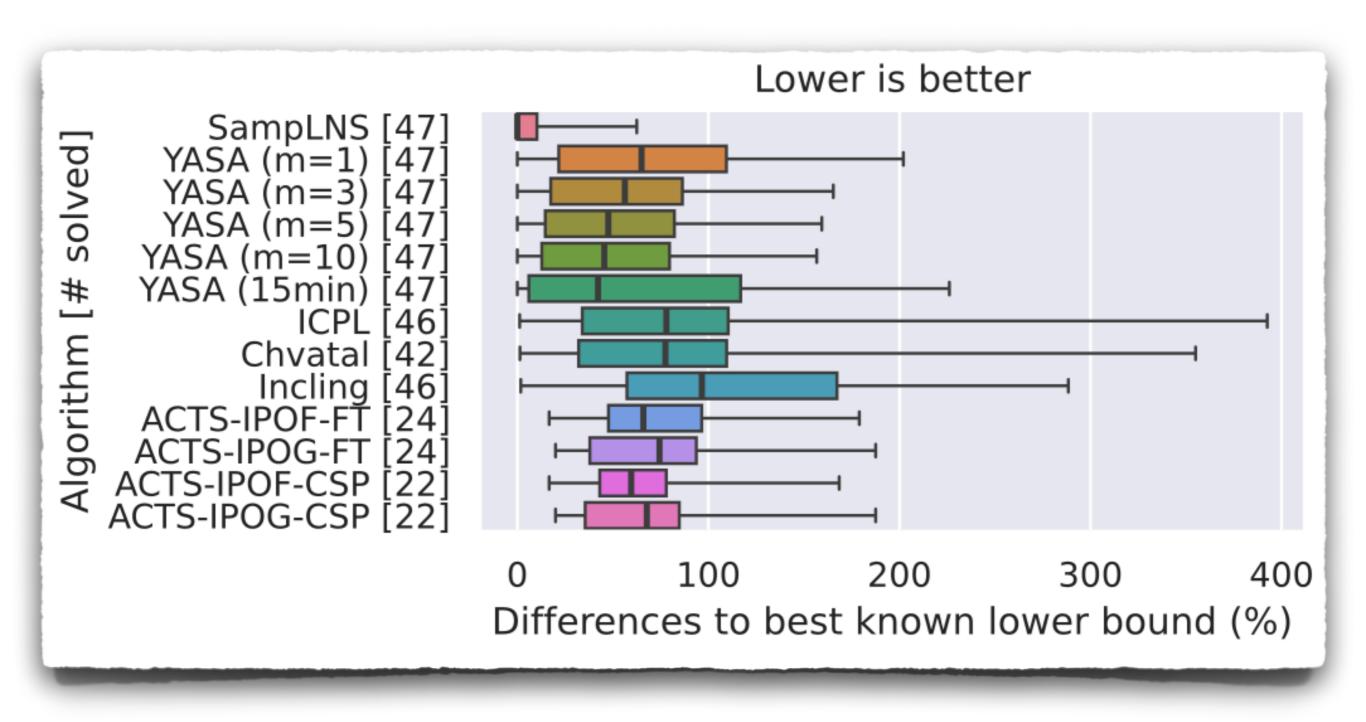
Universität Braunschweig 5 instead of 6!

 $S = (S \setminus S') \cup S'' = \{ \{1, -2, 3, -4\}, \{1, -2, -3, 4\}, \{-1, 2, -3, 4\}, \{1, 2, 3, 4\}, \{-1, 2, -3, 4\} \}$

Repeat!



How good are the lower bounds and solutions?

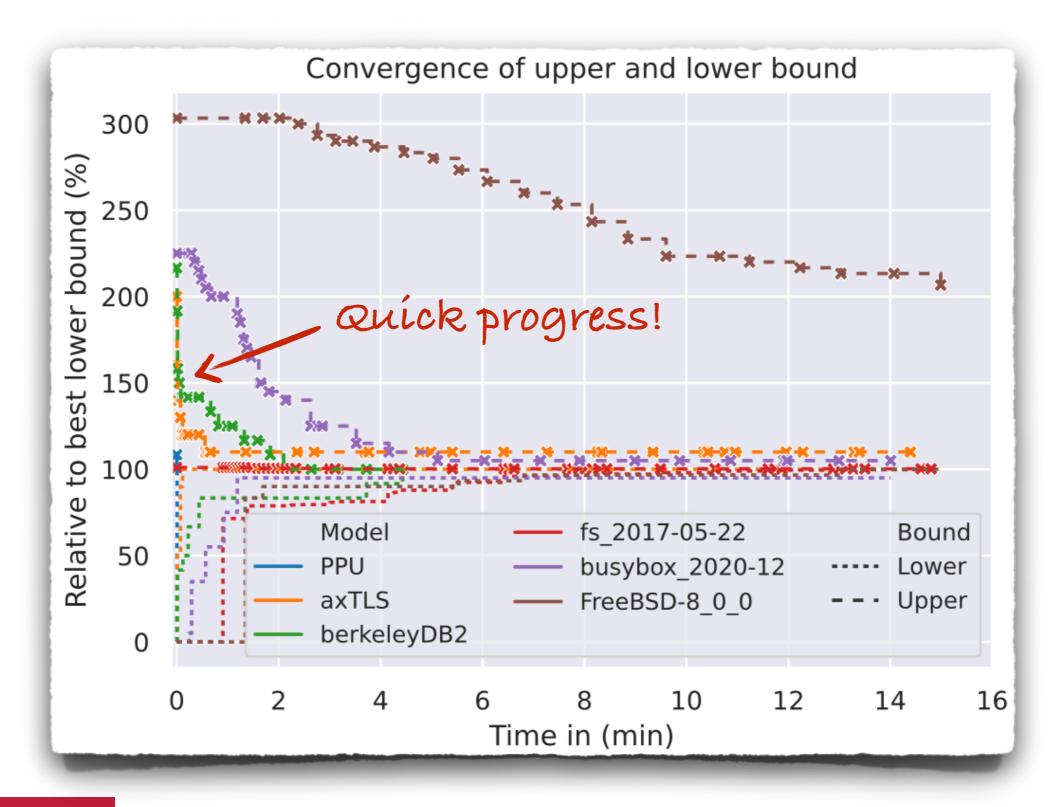




Technische

Universität Braunschweig

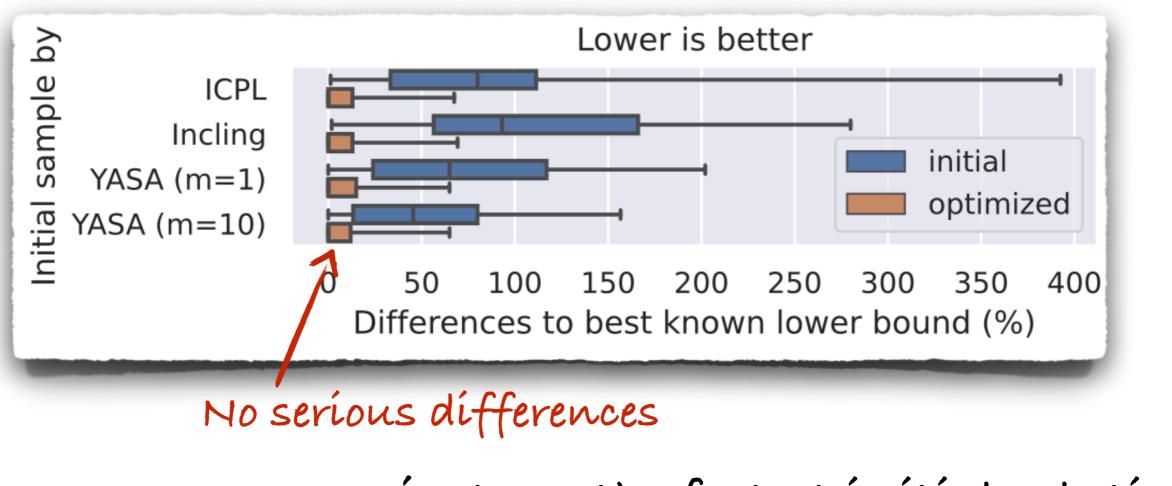
How efficient is the algorithm?





Our algorithm needs an initial solution...

... how important is its quality?



... just use the fastest initial solution!

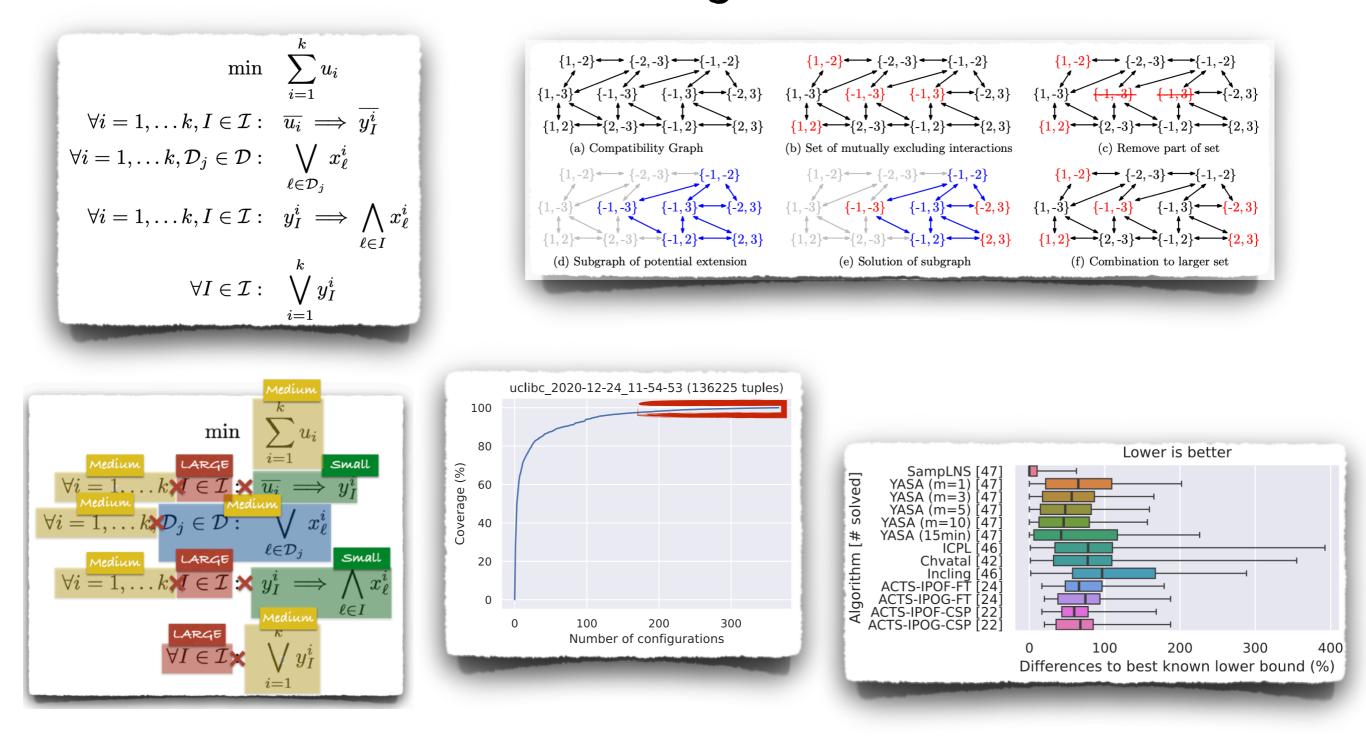


			Baseline	SampLNS UB	SampLNS LB		SampLNS	
Feature Model	$ \mathcal{F} $	$ \mathcal{D} $	min	mean (min)	mean (max)	Savings	UB/LB	Time to Bounds
calculate	9	15	9	5 (5)	5 (5)	44% (44%)	1.00 (1.00)	$< 1 {\rm s} (1 {\rm s})$
lcm	9	16	8	6 (6)	6 (6)	25 % (25 %)	1.00 (1.00)	< 1 s (< 1 s)
email	10	17	6	6 (6)	6 (6)	0% (0%)	1.00 (1.00)	< 1 s (< 1 s)
ChatClient	14	20	7	7 (7)	7 (7)	0% (0%)	1.00 (1.00)	$1 \mathrm{s} (2 \mathrm{s})$
toybox_2006-10-31	16	13	9	8 (8)	8 (8)	11% (11%)	1.00 (1.00)	1 s (1 s)
car	16	33	6	5 (5)	5 (5)	17%(17%)	1.00 (1.00)	< 1 s (< 1 s)
FeatureIDE	19	27	9	8 (8)	8 (8)	11% (11%)	1.00 (1.00)	271 s (128 s)
FameDB	22	40	8	8 (8)	8 (8)	0% (0%)	1.00 (1.00)	1 s (1 s)
APL	23	35	9	7 (7)	7 (7)	22%(22%)	1.00 (1.00)	1 s (1 s)
SafeBali	24	45	11	11 (11)	11 (11)	0% (0%)	1.00 (1.00)	< 1s (< 1s)
TightVNC	28	39	11	8 (8)	8 (8)	27%(27%)	1.00 (1.00)	16 s (21 s)
APL-Model	28	40	10	8 (8)	8 (8)	20 % (20 %)	1.00 (1.00)	14s (15s)
gpl	38	99	17	16 (16)	16 (16)	5.9%(5.9%)	1.00 (1.00)	3s(3s)
SortingLine	39	77	12	9 (9)	9 (9)	25%(25%)	1.00 (1.00)	8 s (9 s)
dell	46	244	32	31 (31)	31 (31)	3.1%(3.1%)	1.00 (1.00)	29 s (45 s)
PPU	52	109	12	12(12)	12(12)	0% (0%)	1.00 (1.00)	255(105) 2s(2s)
berkeleyDB1	76	147	19	15(12)	15(12)	21%(21%)	1.00 (1.00)	$77 \mathrm{s} (137 \mathrm{s})$
axTLS	96	183	15	11 (11)	10 (10)	31%(31%)	1.10 (1.10)	20 s (20 s)
Violet	101	203	$\frac{10}{23}$	17(17)	16(10) 16(16)	26%(26%)	1.06 (1.06)	476 s (656 s)
berkeleyDB2	101	$\frac{203}{346}$	$\frac{23}{20}$	11 (17) 12 (12)	10(10) 12(12)	40%(40%)	1.00 (1.00)	162 s (282 s)
soletta_2015-06-2	$119 \\ 129$	192	$\frac{20}{30}$	24(24)	24(24)	20%(20%)	1.00 (1.00)	21 s (60 s)
BattleofTanks	$129 \\ 144$	769	451	320(295)	256 (256)	20%(20%) 29%(35%)	1.25 (1.15)	887 s (160 min)
	$144 \\ 176$	280	40				· · ·	· · ·
BankingSoftware			$\frac{40}{234}$	29(29)	29 (29)	28%(28%)	1.00(1.00)	306 s (429 s)
fiasco_2017-09-26	230	1,181		225 (225)	225 (225)	3.8%(3.9%)	1.00(1.00) 1.00(1.00)	382 s (579 s)
fiasco_2020-12-01	258	1,542	209	196 (196)	196 (196)	6.1%(6.2%)	1.00 (1.00)	438 s (478 s)
uclibc_2008-06-05	263	1,699	505	505 (505)	505 (505)		1.00 (1.00)	104 s (67 s)
uclibc_2020-12-24	272	1,670	365	365 (365)	365 (365)	0%(0%)	1.00 (1.00)	108 s (112 s)
E-Shop	326	499	19	12 (12)	9 (10)	37%(37%)	1.30 (1.20)	268 s (64 min)
toybox_2020-12-06	334	92	18	13 (13)	7 (8)		1.71 (1.62)	532 s (35 min)
DMIE	366	627	26	16 (16)	16 (16)	38% (38%)	1.00 (1.00)	$104 \mathrm{s} (135 \mathrm{s})$
soletta_2017-03-0	458	1,862	56	37 (37)	31 (37)	34% (34%)	1.16 (1.00)	387 s (24 min)
busybox_2007-01-2	540	429	34	21 (21)	21 (21)	38% (38%)	1.00 (1.00)	$164 \mathrm{s} (237 \mathrm{s})$
fs_2017-05-22	557	4,992	398	396 (396)	396 (396)	0.5%(0.5%)	1.00 (1.00)	$478 \mathrm{s} (575 \mathrm{s})$
WaterlooGenerated	580	879	144	82 (82)	82 (82)	43 % (43 %)	1.00 (1.00)	$223 \mathrm{s} (310 \mathrm{s})$
financial_services	771	7,238	4,384	4,368 (4,340)	4,274 (4,336)	0.36%(1%)	1.02 (1.00)	862 s (102 min)
busybox-1_18_0	854	1,164	26	16 (16)	11 (13)	35 % (38 %)	1.53 (1.23)	$233 \mathrm{s} (59 \mathrm{min})$
busybox-1_29_2	1,018	997	36	22 (22)	17 (21)	38 % (39 %)	1.26 (1.05)	$465 {\rm s} (60 {\rm min})$
busybox_2020-12-1	1,050	996	33	21 (20)	17 (19)	36%(39%)	1.19 (1.05)	$407 \mathrm{s} \; (17 \mathrm{min})$
am31_sim	$1,\!178$	2,747	60	36 (33)	26 (29)	39%~(45%)	1.36 (1.14)	$699 \mathrm{s} (77 \mathrm{min})$
EMBToolkit	$1,\!179$	$5,\!414$	1,881	1,879 (1,872)	1,821 (1,872)	$0.1\%\;(0.48\%)$	1.03 (1.00)	863 s (47 min)
atlas_mips32_4kc	1,229	$2,\!875$	66	38 (36)	31 (33)	$41\%\;(45\%)$	1.22 (1.09)	548 s (50 min)
eCos-3-0_i386pc	1,245	3,723	64	43 (39)	31 (36)	$32\%\;(39\%)$	1.38 (1.08)	621 s (146 min)
integrator_arm7	1,272	2,980	66	38 (36)	30 (33)	$41\%\;(45\%)$	1.28 (1.09)	681 s (82 min)
XSEngine	1,273	2,942	63	38 (36)	31 (32)	$39\%\;(43\%)$	1.23 (1.12)	572 s (52 min)
aaed2000	1,298	3,036	87	55 (52)	51 (51)	36%(40%)	1.09 (1.02)	707 s (75 min)
FreeBSD-8_0_0	1,397	$15,\!692$	76	47 (41)	27 (30)	$38\%\;(46\%)$	1.72 (1.37)	831 s (120 min)
ea2468	1,408	3,319	65	38 (36)	31 (32)	41 % (45 %)	1.24 (1.12)	721 s (67 min)
optimality			7	≥ 26				
improvements			[15%]	[55 %]		10 [05 07]		
improvements						40 [85 %]		



How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12

Summary





Technische

Universität Braunschweig How Low Can We Go? Minimizing Interaction Samples for Configurable Systems Dominik Krupke FOSD 2024-04-12